Predicting Earthquakes with Hierarchical Neural Network Models

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Applying machine learning in earthquake forecasting faces many obstacles

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◆ Missing data near the lower detection threshold
	- ↓ **Catalogs don't reach far enough back in time**
	- ↓ Changes in data collection methods over time
- \blacktriangleright We try to circumvent this problem by:
	- µ extracting as much information as possible from the catalogs
	- ↓ devising a prediction model that can process that information

- ▶ We limit our analysis to fault-independent information
	- ↓ Catalogs with only basic earthquake characteristics: timestamp, magnitude, depth, latitude, longitude
	- ↓
→ Widely available for various seismic regions around the globe
→ ⇒ More data to work with
	-
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↓ Widely available for various seismic regions around the globe
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	- µ *⇒* Applicability to various regions
- Existing methods do not seem to leverage all the information provided by these datasets
- Improvements can be achieved in:
	- ↓
◆ modeling of the problem
	- ↓ feature engineering

- \blacktriangleright Based on the earthquake catalog information, we derive two kinds of features:
	- → Distances between earthquake point patterns
		-
- ▶ Our prediction model, however, can be extended to other features

- \triangleright We pre-process the earthquake catalog to obtain the sets of earthquakes in time windows of a certain length
	- **→** 7 days for next-day forecasting
- Each set is a series of points scattered over a tridimensional space, with extra information associated to each point:
	- **↓** magnitude
	- ↓ timestamp
- ▶ These sets can be compared by using statistical tools
	- µ We use **edit distances**
- \blacktriangleright Main idea is that similar earthquake patterns will result in similar outcomes¹

¹M. H. Junqueira Saldanha and Y. Hirata (2022). "Solar activity facilitates daily forecasts of large earthquakes \mathbb{C} ". In: *Chaos: An Inter*-*4 disciplinary Journal of Nonlinear Science* 32.6, p. 061107.

Feature Engineering

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 \blacktriangleright Let P_1 and P_2 be two marked point processes:

$$
P_1 = \{(t_i, u_i) \mid 1 \le i \le N_1\} \qquad P_2 = \{(s_j, v_j) \mid 1 \le j \le N_2\}
$$

- \blacktriangleright The idea is to transform P_1 into P_2 using primitive operations, each incurring a cost.
- \blacktriangleright The primitive operations are:
	- **Insertion**: insert point (s_j, v_j) from P_2 into P_1 , paying a cost of 1;
	- **Deletion:** remove point (t_i, u_i) from P_1 , paying a cost of 1;
	- Solution: $\lim_{t \to \infty} \lim_{t \to \infty} P_2$, paying a cost that depends on how different these two points are.
- \blacktriangleright The **edit distance²³ i**s defined as the lowest possible cost necessary to transform P_1 to $P_2.$

² J. D. Victor and K. P. Purpura (1997). "Metric-space analysis of spike trains: theory, algorithms and application". In: *Network: compu-*
tation in neural systems 8.2, pp. 127–164.

^{3&}lt;sub>S.</sub> Suzuki, Y. Hirata, and K. Aihara (2010). "Definition of distance for marked point process data and its application to recurrence plot-*6* based analysis of exchange tick data of foreign currencies". In: *International Journal of Bifurcation and Chaos* 20.11, pp. 3699–3708.

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- ▶ Now consider the sets of earthquakes over time-windows of size *T* \blacktriangleright $T = 7, 15, 30, 60, 90, 180, 360$ days
- Seismicity indicators can be calculated for each of these sets ↓ mean and maximum magnitudes;
	-
	- **→** rate of release of seismic energy, given by

 $\sum_{i=1}^{k} \left(10^{10.8+1.5e_i^{\text{mag}}} \right)$ $\frac{1}{\Delta t}$,

where ∆*t* is the length of the time window;

■ time elapsed between all earthquakes that exceed a certain magnitude threshold $τ$;

- \leftrightarrow a, *b* values of the Gutenberg-Richter's law fit;
	- **■** sum of square errors of the magnitudes to the regression line of the GR law;
	- **→** magnitude deficit, defined as the difference between the expected maximum magnitude (according to the GR law) and the observed maximum magnitude; and
	- **→** coefficient of variation of inter-event times, after removing earthquakes with magnitude below a certain threshold *τ* .

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- Distance to each fault line (undergoing improvements)

 \blacktriangleright

- ▶ If we calculate these features for different sizes of time-windows, we are left with a large volume of features to work with
- However, more features *⇒* bigger models *⇒* more data needed for good fit (Bengio, Goodfellow, and Courville 2017) 4

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- However, more features *⇒* bigger models *⇒* more data needed for good fit (Bengio, Goodfellow, and Courville 2017) 4
- \triangleright To tackle this, we design a neural network architecture particular for the problem at hand
- ▶ Objectives:
	- →
← Features are mathematically processed in a logical manner
	- ↓ Minimal number of trainable weights
	- ↓ Extensibility of the model to use different kinds of features

⁴ *9* Y. Bengio, I. Goodfellow, and A. Courville (2017). *Deep learning*. Vol. 1. MIT press Cambridge, MA, USA.

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- \blacktriangleright The features associated with time-window T_i are fed to one single neural sub-network
	- **■** There is no need to evaluate linear‑combinations of features of different time window lengths
	- **◆** Nor linear combinations between seismicity indicators and edit distances
- \blacktriangleright The outputs of the sub-network are then fed to a neural network that will then derive the predictions

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 5 Catalogs from the Japanese Meteorological Agency, the New Zealand GeoNet project and the University of Athens. Minimum magni-*11* tude threshold: 2.5

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- ▶ Overall accuracy: 79.53%
- Class weighted accuracy: 56.50%

- ▶ Overall accuracy: 92.35%
- Class weighted accuracy: 60.50%

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- \blacktriangleright Processing becomes difficult as the number of features increases

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- Processing becomes difficult as the number of features increases
- ▶ We present a neural network architecture that
	- ↓
◆ Processes features in a logical manner
	- **→** Minimizes number of trainable weights
	- **→** Is flexible and easy to extend for different features and use in different regions

- Results so far are promising, bringing improvements to our past results (Junqueira Saldanha and Hirata 2022) 6
- \blacktriangleright Possible improvements relative to recent work: (Yavas et al. 2024)⁷
	- **→** 30-day forecasting
	- ◆ Overall accuracy: 55.97%
	- ↓ Systal accuracy: 55.57%
► Large magnitudes accuracy: 11.9% 27.0% (estimated)
- 6M. H. Junqueira Saldanha and Y. Hirata (2022). "Solar activity facilitates daily forecasts of large earthquakes &". In: *Chaos: An Inter-*
- *disciplinary Journal of Nonlinear Science* 32.6, p. 061107. ⁷C. E. Yavas et al. (2024). "Predictive modeling of earthquakes in los angeles with machine learning and neural networks". In: *IEEE 15 Access*.

Thank You!

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